

NGA-West2 Models for Ground-Motion Directionality

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ABSTRACT

The NGA-West2 research program, coordinated by the Pacific Earthquake Engineering Research Center (PEER), is a major effort to produce refined models for predicting ground-motion response spectra. This study presents new models for ground-motion directionality developed as part of that project. Using a database of recorded strong ground motions, empirical models have been developed for a variety of quantities related to direction-dependent spectra. Predictions are available for the maximum spectral acceleration observed in any orientation of two-component horizontal ground-motion shaking ($Sa_{RotD100}$). This model is formulated as a multiplier factor to be coupled with the NGA-West2 models that predict the median spectral accelerations over all orientations ($Sa_{RotD100}$). Models are also proposed for the distribution of orientations of the $Sa_{RotD100}$ value relative to the fault and the relationship between $Sa_{RotD100}$ orientation at different periods. Discussion is provided as to how these results can be applied to practical seismic hazard analysis and compute realistic target spectra conditioned on different parameters.

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1 INTRODUCTION

Structures designed to resist seismic loads are generally designed considering ground motion in the horizontal plane. However, the acceleration response spectrum, which is the intensitymeasure (IM) used for design, is defined as the maximum response of a damped single-degreeof-freedom (SDOF) system at different periods when excited by a single component of the ground motion (5% damping is assumed throughout, also *Sa* in this report refers to pseudo spectral acceleration or PSA). So, even though two dimensional ground motions are considered for design, the IM is defined to represent single component of the ground motion. Various methods have been proposed to compute an intensity-measure representative of the twodimensional horizontal ground motion. These methods include using the geometric mean of the acceleration response spectra computed using two orthogonal components of ground motion, using the median or maximum value of response spectra over all orientations at each period, etc. [Boore et al. 2006; Boore 2010].

The NGA-West2 research program, coordinated by Pacific Earthquake Engineering Research Center (PEER), produces refined models for predicting the median ground-motion response spectra of a ground motion when rotated over all horizontal orientations (Bozorgnia et al. 2012); this is referred to as the Sa_{RotD50} spectrum [Boore 2010]. It is known that groundmotion intensity is not uniform in all orientations. In some cases ground motions can be polarized and intensity in one orientation can be significantly stronger than in other orientations (e.g., Campbell and Bozorgnia [2007, 2008]; and Huang et al. [2008]). This phenomenon is often referred as "directionality" of ground motion. Due to ground motion directionality, some engineers believe that the maximum spectral acceleration over all orientations ($Sa_{RotD100}$) is a more meaningful IM than Sa_{RotD50} for structural design (e.g., NEHRP [2009]). Thus, different definitions of ground-motion intensities will be used to build ground-motion models (Sa_{RotD50}) and for structural design $(Sa_{RotD100})$. The need to use a consistent IM throughout the design process (e.g., Baker and Cornell [2006]; and Beyer and Bommer [2006]) requires models to convert between the two definitions of IM. Additionally, there is interest in whether the $Sa_{RotD100}$ is observed in random orientations or has preferential alignment in, for example, nearfault ground motions. This also has potentially important implications for structural design.

Several researchers have modeled the ratio of different IMs, which can be used as a multiplicative factor to convert between them (e.g., Beyer and Bommer [2006]; Watson-Lamprey and Boore [2007]; Campbell and Bozorgnia [2007, 2008]; and Huang et al. [2008, 2010]). Most of these studies used subsets of the NGA database [Chiou et al. 2008] and focused on the ratios involving the older $Sa_{GMRotI50}$ definition of response spectrum. This study used over 3000 ground motions from the expanded NGA-West2 database to build empirical models for the ratio of $Sa_{RotD100}$ to Sa_{RotD50} and the probability distribution of orientations in which the

 $Sa_{RotD100}$ is observed. The model predicting the ratio of $Sa_{RotD100}$ to Sa_{RotD50} can be used as a multiplicative factor that when used with the NGA-West2 ground-motion models can predict the $Sa_{RotD100}$ at a site. The proposed models are compared with older models and differences are discussed.

As defined, the $Sa_{RotD100}$ values at different periods may occur in differing orientations. So it is highly unlikely that any single orientation will have Sa as large as the $Sa_{RotD100}$ at all periods. Since nonlinear response of a multi-degree-of-freedom (MDOF) system is related to Sa at a range of periods, using $Sa_{RotD100}$ as the spectrum of a single ground-motion component may lead to conservative estimates of structural demand (e.g., Stewart et al. [2011]). To address this, the relationship between the orientations of $Sa_{RotD100}$ at different periods is studied in detail, and this information is used to compute more realistic target spectra for single ground-motion components. Example computation and discussion of several alternate target spectra is included.

2 Ground-Motion Intensity and Directionality

As discussed above, spectral acceleration (*Sa*) measures the response of a SDOF oscillator in a single orientation and cannot completely represent the intensity in two dimensions if the ground motion is polarized. Several IMs have been proposed in the past to better account for two dimensional intensity of ground motions, while not sacrificing the ease of use of a scalar IM. Early efforts to account for the two-dimensional intensity of ground motion used the geometric mean of response spectra computed using two orthogonal components of the ground motion (sometimes referred as Sa_{GM}). Generally the two orientations in which the ground motion was recorded ("as-recorded orientations"), or the fault-normal and parallel orientations, are used for computing Sa_{GM} . Using the as-recorded orientations of the ground motion makes the ground-motion intensity dependent on the orientation of the recording instrument, which is often arbitrary (though the practical effect on *Sa* is often not major). The fault-normal and parallel orientations (directivity in fault-normal, fling in fault-parallel for strike-slip earthquakes), but these orientations have no special significance for sites located far from the fault.

To remove the dependence of IM on arbitrarily selected orientations, Boore et al. (2006) introduced $Sa_{GMRotDnn}$ and $Sa_{GMRotInn}$ IMs, which are orientation independent definitions of ground-motion intensity. $Sa_{GMRotDnn}$ is defined as the nn^{th} percentile of the geometric means of the response spectra from all orthogonal components of the ground motion at a specified period. The $Sa_{GMRotDnn}$ spectrum uses the geometric means from different orientations at different periods and does not represent any particular observation of two components of the geometric mean of response spectra at the specific orientation with a spectrum closest to the $Sa_{GMRotDnn}$ spectrum of two specific ground-motion components that were observed at the site. The 2008 version of NGA ground-motion models were developed to predict the $Sa_{GMRotI50}$ at a site [Abrahamson et al. 2008].

Although the $Sa_{GMRotInn}$ spectrum captures information from multiple orientations and is orientation and period independent, it is difficult to compute. Boore [2010] proposed a new set of IM called Sa_{RotDnn} and Sa_{RotInn} . Sa_{RotDnn} is defined as the nn^{th} percentile of the spectral acceleration at each period over all orientations. Like $Sa_{GMRotDnn}$, the nn^{th} percentile spectral acceleration at each period may occur in different orientations. Sa_{RotInn} addresses this by defining the intensity to be the spectral acceleration in the orientation most representative of the Sa_{RotDnn} spectrum. Since maximum intensity at each period may occur in different orientations and Sa_{RotInn} spectrum uses a single orientation of the ground motion, the Sa_{RotI50} spectrum can be greater than the $Sa_{RotI100}$ spectrum at some periods [Boore 2010]. This is considered a shortcoming of the Sa_{RotInn} definition. Due to its simple and orientation-independent definition the Sa_{RotDnn} IM has become popular. The new ground-motion models being developed as part of the NGA-West2 project will predict Sa_{RotD50} values, but the NEHRP [2009] provisions use $Sa_{RotD100}$ intensity for seismic design.

In general, constructing a single response spectrum to represent two-dimensional groundmotion intensity involves reducing information in two dimensions to one, which results in loss of some information. Different definitions of ground-motion intensity capture different pieces of this information and thus may be appropriate for different tasks. If the ground motion is unpolarized, then it will have equal intensity in all orientations (i.e., no directionality). In an almost no-polarization case, illustrated in Figure 2.1a, all definitions of ground-motion intensity will give similar result. Hence, the ratio of $Sa_{RotD100}$ to Sa_{RotD50} will be close to 1. However, if the ground motion is strongly polarized, as illustrated in Figure 2.1b, the various definitions of Sa will differ significantly in value. In this case, different definitions of IM will give different results, and the ratio of $Sa_{RotD100}$ to Sa_{RotD50} can be shown to equal $\sqrt{2} = 1.414$. A groundmotion record generally lies between these two extreme cases, and the $Sa_{RotD100}$ to Sa_{RotD50} ratio lies between 1 and 1.414, as shown in Figure 2.2. So the intensity of ground motion computed using Sa_{RotD50} or $Sa_{RotD100}$ can differ for various ground motions, with the difference ranging from 0 to 41% of the Sa_{RotD50} intensity.

The polarization of ground motion, also referred as directionality of ground motion, causes this discrepancy among different definitions of response spectra. Thus, in this study the models used to convert between different spectral acceleration definitions are referred to as directionality models.



Figure 2.1 Displacement response trace (*T* = 1 sec) and spectral acceleration in all orientations: (a) when ground motion is almost unpolarized (HWA031 recording from Chi-Chi-04, 1999 earthquake); and (b) when the ground motion is almost completely polarized (Gilroy Array#6 recording from Morgan Hill,1984 earthquake).



Figure 2.2 Histogram of observed ratios of $Sa_{RotD100}$ and Sa_{RotD50} in the NGA-West2 database for (a) T = 0.2 sec, (b) T = 1 sec, (c) T = 3 sec, and (d) T = 5 sec.

3 Ratio of $Sa_{RotD100}$ to Sa_{RotD50}

As discussed earlier, the NEHRP (2009) provisions use $Sa_{RotD100}$ as the IM for design while the NGA-West2 ground-motion models are being developed to predict Sa_{RotD50} intensity. Thus, models to convert between the two definitions are needed to allow the use of consistent definition of IM throughout the design process.

We computed the ratio of $Sa_{RotD100}$ to Sa_{RotD50} for each ground motion in the subset of NGA-West2 database being used to develop the Abrahamson-Silva ground-motion model. The geometric mean of these ratios can be used as a multiplicative factor to convert Sa_{RotD50} intensity to $Sa_{RotD100}$ and its logarithm as an additive factor to convert $lnSa_{RotD50}$ to $lnSa_{RotD100}$. As ground-motion intensities are assumed to be log-normally distributed (e.g., Abrahamson [1998]; and Jayaram and Baker [2008]) and the ground-motion models predict the natural log of intensity, the geometric mean of the ratios is a more natural estimator than the arithmetic mean, as shown in Equations (3.1) to (3.3).

$$Sa_{RotD100} = \frac{Sa_{RotD100}}{Sa_{RotD50}} \cdot Sa_{RotD50}$$
(3.1)

$$lnSa_{RotD100} = ln\left(\frac{Sa_{RotD100}}{Sa_{RotD50}}\right) + lnSa_{RotD50}$$
(3.2)

$$E[lnSa_{RotD100}] = E\left[ln\left(\frac{Sa_{RotD100}}{Sa_{RotD50}}\right)\right] + E[lnSa_{RotD50}]$$
(3.3)

where $E[\cdot]$ represents the expected value or mean value. Mixed effects regression (e.g., Searle [1971]; Brillinger and Preisler [1985]; and Abrahamson and Youngs [1992)] is used to estimate the $ln(Sa_{RotD100}/Sa_{RotD50})$ while accounting for any earthquake-specific effects in the ratio of $Sa_{RotD100}$ and Sa_{RotD50} . The empirically computed geometric mean of $Sa_{RotD100}/Sa_{RotD50}$ from mixed-effects regression at different periods is shown in Figure 3.1.Table 3.1 shows the estimated $E[ln(Sa_{RotD100}/Sa_{RotD50})]$ along with the between-event standard deviation (τ) and within-event standard deviation (ϕ) (standard-deviation notation following Al Atik et al. [2010]). The low values of τ shows that the event terms for $ln(Sa_{RotD100}/Sa_{RotD50})$ are close to zero or the event terms for $lnSa_{RotD100}$ and $lnSa_{RotD50}$ are almost same as each other, and thus cancel out. This was expected, as the amplification/deamplification due to common source effects should be shared by both Sa_{RotD50} and $Sa_{RotD100}$. Results computed using different

subsets of the NGA-West2 database used to develop other ground-motion models were found to be consistent with each other.



Figure 3.1 Geometric mean of the observed ratio of $Sa_{RotD100}$ to Sa_{RotD50} estimated by mixed effects regression using NGA-West2 database.

Table 3.1Fitted values of $ln(Sa_{RotD100}/Sa_{RotD50})$ with the within-event standard
deviation (ϕ) , between-event standard deviation (τ) and total standard
deviation (σ) , estimated by mixed effects regression. Note that the
estimates are for mean of $ln(Sa_{RotD100}/Sa_{RotD50})$ and geometric mean of
 $Sa_{RotD100}/Sa_{RotD50}$ and the reported standard deviations are for
 $ln(Sa_{RotD100}/Sa_{RotD50})$ estimates.

T(s)	$T(s) \qquad ln(\frac{Sa_{RotD100}}{Sa_{RotD50}}) \qquad \frac{Sa_{RotD100}}{Sa_{RotD50}}$		ϕ	τ	σ_{total}	
0.01	0.176	1.19	0.08	0.01	0.08	
0.02	0.175	1.19	0.08	0.01	0.08	
0.03	0.172	1.19	0.08	0.01	0.08	
0.05	0.171	1.19	0.08	0.01	0.08	
0.075	0.172	1.19	0.08	0.01	0.08	
0.1	0.172	1.19	0.08	0.01	0.08	
0.15	0.182	1.20	0.08	0.01	0.08	
0.2	0.187	1.21	0.08	0.01	0.08	
0.25	0.196	1.22	0.08	0.01	0.08	
0.3	0.198	1.22	0.08	0.01	0.08	
0.4	0.206	1.23	0.08	0.01	0.08	
0.5	0.206	1.23	0.09	0.01	0.09	
0.75	0.213	1.24	0.08	0.01	0.08	
1	0.216	1.24	0.08	0.01	0.08	
1.5	0.217	1.24	0.08	0.01	0.08	
2	0.218	1.24	0.08	0.01	0.08	
3	0.221	1.25	0.08	0.01	0.08	
4	0.231	1.26	0.08	0.01	0.08	
5	0.235	1.26	0.08	0.02	0.08	
7.5	0.251	1.28	0.08	0.02	0.08	
10	0.258	1.29	0.07	0.03	0.08	

3.1 COMPARISON WITH OTHER MODELS

Several researchers have computed estimates for the ratio of $Sa_{RotD100}$ to $Sa_{GMRotI50}$ in past (e.g., Beyer and Bommer [2006]; Watson-Lamprey and Boore [2007]; Campbell and Bozorgnia [2007, 2008]; and Huang et al. [2008, 2010]). To compare the older ratios of $Sa_{RotD100}$ to $Sa_{GMRotI50}$ with the $Sa_{RotD100}$ to Sa_{RotD50} ratios computed in this study, we use the factors proposed by Boore [2010] to convert the proposed $Sa_{RotD100}/Sa_{RotD50}$ ratios to $Sa_{RotD100}/Sa_{RotD50}$ ratios. Figure 3.1 compares our converted $Sa_{RotD100}$ to $Sa_{GMRotI50}$ ratios with previous results. Most of these models agree with each other in both the magnitude of the ratios and their trend with period. The one exception is the ratios proposed in NEHRP [2009] provisions.

The NEHRP [2009] $Sa_{RotD100}/Sa_{GMRotI50}$ ratios are based on the ratio of observed $Sa_{RotD100}$ values in recorded ground motions to the prediction of $Sa_{GMRotI50}$ by a ground-motion model. Modeling the ratio of an observed value to a predicted value—rather than the

ratio of an observed value to an observed value—has some flaws. The NGA models were carefully fitted to provide an unbiased estimate of ground-motion intensity from future earthquakes [Abrahamson et al. 2008]. However, the dataset used to fit the ground-motion models is not an unbiased sample of earthquakes (e.g., there are many more ground motions from the 1999 M=7.6 Chi-Chi, Taiwan earthquake in the NGA database compared to other earthquakes). Statistical techniques such as mixed-effects regression have been used to overcome these biases in the dataset while fitting the NGA ground-motion models. The ratios recommended by NEHRP [2009] provisions effectively readjust the NGA ground-motion models, which undoes careful calculations that go into building a ground-motion model. For example, a particular earthquake can produce higher average ground-motion intensities than the unbiased ground-motion model estimate due to random chance (any effect not accounted for by the ground-motion model can be modeled as random chance). The ratios of observed $Sa_{RotD100}$ to the predicted Sa_{RotD50} for such an earthquake will be higher than the ratio of observed $Sa_{RotD100}$ to observed Sa_{RotD50} , as the first ratio will also include the random earthquake effect, which is carefully removed by the mixed effects regression used to fit ground-motion models. Modeling $Sa_{RotD100}/Sa_{RotD50}$ as the ratio of observed $Sa_{RotD100}$ to observed Sa_{RotD50} , and using the prediction from a ground-motion model as an estimate for $E[lnSa_{RotD50}]$ in Equation (3.3) allows us to leverage the results from careful fitting of ground-motion models and gives us a better estimate of $Sa_{RotD100}$ from a future earthquake.

Huang et al. [2008, 2010] reported that ground motion from Chi-Chi, Taiwan, earthquake had a significant effect on the geometric mean of the ratio of observed $Sa_{RotD100}$ to $Sa_{GMRotI50}$ values predicted by ground-motion models, so they reported different sets of results for datasets with and without the Chi-Chi records. As shown in Figure 3.2, we found that presence or absence of Chi-Chi records did not change significantly the geometric mean of observed $Sa_{RotD100}$ to observed Sa_{RotD50} . This indicates that the observed to observed ratio are more stable across different earthquake events compared to the observed to predicted ratio.



Figure 3.1 Comparison of various models for geometric mean $Sa_{RotD100}/Sa_{RotD50}$ ratios.



Figure 3.2 Comparison of the geometric means of $Sa_{RotD100}/Sa_{RotD50}$ estimated using datasets with and without the 1999 *M*=7.6 Chi-Chi ground motions.

3.2 DEPENDENCE OF $Sa_{RotD100}/Sa_{RotD50}$ ON OTHER PARAMETERS

Figure 2.2 and Figure 3.1 showed that the geometric mean value of $Sa_{RotD100}/Sa_{RotD50}$ depends on spectral acceleration period. We also investigated its dependence on other seismological parameters like earthquake magnitude, closest distance between source and the site and some directivity parameters. We studied the dependence of this ratio on other seismological parameters and fitted several regression models using variable selection techniques like forward selection, backward elimination, etc. After examining the practical and statistical significance of different models, we decided to develop a model for $ln(Sa_{RotD100}/Sa_{RotD50})$ that was a linear function of R_{rup} (closest distance between rupture and site). Other parameters such as magnitude, directivity predictor terms, etc., had no appreciable predictive power. Figures showing the weak dependence of $Sa_{RotD100}/Sa_{RotD50}$ on several seismological parameters are included in Appendix A. The linear model, shown in Equation (3.4) contains a coefficient a_0 that varies with period and a coefficient a_1 that is constant for all periods, and is estimated to be -1.614×10^{-4} . Coefficient a_0 is the same as the $ln(Sa_{RotD100}/Sa_{RotD50})$ values presented in Table 3.1

Note that this relationship was fitted using data with closest distance less than 200 km and over 90% of the data had closest distance less than 100 km. So, we do not recommend use of these models for distances larger than 200 km.

$$E\left[ln\left(\frac{Sa_{RotD100}}{Sa_{RotD50}}\right)\right] = a_0 + a_1 \cdot (R_{rup} - 60)$$
(3.4)

The difference between the results from using a distance-dependent model or using a nondistance-dependent model is small, as can be seen in Figure 3.3. Thus, we report both the geometric mean of the ratio of $Sa_{RotD100}$ and Sa_{RotD50} and the coefficient a_0 from Equation (3.4) at different periods in Table 3.1. Either of the two models can be used depending on the level of precision required. This view is echoed in the similar earlier study by Watson-Lamprey and Boore [2007], who noted slight distance, magnitude and radiation pattern dependence, but stated that "for most engineering applications the conversion factors independent of those variables can be used." The results are reported at discrete set of periods and coefficients at other periods can be estimated by interpolating these results.



Figure 3.3 Prediction of $Sa_{RotD100}/Sa_{RotD50}$ by the distance dependent model in Equation (3.4) for R = 5km, compared with the non-distance-dependent estimates of $Sa_{RotD100}/Sa_{RotD50}$ given in

4 Orientation of $Sa_{RotD100}$

Structural systems generally have different resistance to seismic loads in different orientations. For these systems, the orientation in which the maximum spectral acceleration occurs is also important. We define the orientation of $Sa_{RotD100}$ as the minimum angle between the strike of the fault and the orientation of $Sa_{RotD100}$. This orientation, referred as α hereafter, ranges from 0 to 90° where $\alpha = 0$ represents the strike-parallel orientation and $\alpha = 90$ represent the strike-normal orientation.

To study these orientations, we computed α for each ground motion in our database at 21 periods, and then binned the data according to different seismological parameters and examined the distribution of α in each bin. Figure 4.1 shows the distribution of α in different *M* and R_{rup} bins. α is closer to the strike-normal orientation ($\alpha = 90$) more often than to the strike-parallel orientation ($\alpha = 0$) when the site is located within 5 km of the fault. On the other hand, when R_{rup} is greater than 5 km, α is almost uniformly distributed. The magnitude bins do not seem to have any significant influence on the distribution of α . To examine the effect of period on $Sa_{RotD100}$ orientation (α), we binned all the data within 5 km of the fault by period. Histograms of α in different period bins are shown in Figure 4.2. The distribution of α is nearly uniform for periods less than 1 sec, while orientations close to strike-normal are more frequent than strike-parallel for periods larger than 1 sec.

After examining histograms of α binned by several parameters (two other examples are shown in Appendix B), we decided to model the distribution of α as uniform for sites when R_{rup} is greater than 5 km or when the spectral-acceleration period under consideration is less than 1 sec. For other cases ($R_{rup} < 5$ km and $T \ge 1$ sec) the data was pooled and the distribution was modeled empirically by counting the number of α observed in 10° bins. This empirically computed distribution is presented in Table 4.1.



Figure 4.1 Probability density of α (*Sa*_{*RotD100*} orientations) in different *M*, *R*_{*rup*} bins.



Figure 4.2 Probability density of α for sites with $R_{rup} < 5$ km, binned by period (sec).

Orientations (degrees)	Probability
0-10	0.031
10-20	0.055
20-30	0.070
30-40	0.067
40-50	0.080
50-60	0.100
60-70	0.106
70-80	0.233
80-90	0.258

Table 4.1 Probability density of α for $R_{rup} < 5$ km and $T \ge 1$ sec.

4.1 RELATIONSHIP BETWEEN $Sa_{RotD100}$ ORIENTATIONS AT DIFFERENT PERIODS

Figure 4.3 shows the polarization of displacement response and orientation of $Sa_{RotD100}$ intensity from an example ground motion at two different periods (say T^* and T'). The $Sa_{RotD100}$ intensity at different periods may occur in different orientations and the difference in orientation $(|\alpha^* - \alpha'|)$ in Figure 4.3) can be used to study the relationship between the $Sa_{RotD100}$ orientations at different periods. This knowledge can be used to construct more realistic single orientation target spectra, as shown below.

The difference in the orientation of $Sa_{RotD100}$ at two periods has a lot of uncertainty and can take any value between 0° (i.e., the orientation at both period are the same) to 90° (i.e., the $Sa_{RotD100}$ occurs in orthogonal orientations at the two periods). Figure 4.4 shows the histogram of the difference in $Sa_{RotD100}$ orientation ($|\alpha^* - \alpha'|$) at two different periods. The probability distribution of $|\alpha^* - \alpha'|$ depends on the periods under consideration $|\alpha^* - \alpha'|$ is more likely to be close to 0° when the periods are closer to each other. Thus, the average difference between the orientations increases with increasing difference between the periods.

After examining histograms at several sets of periods, the truncated exponential distribution was selected to model the distribution of $|\alpha^* - \alpha'|$. The truncated exponential distribution is described below

$$f(x) = \begin{cases} \frac{\lambda e^{-\lambda x}}{1 - e^{-90\lambda}}; & x \le 90\\ 0 & \text{otherwise} \end{cases}$$
(4.1)

The distribution depends on the parameter λ , which is estimated here using the maximum likelihood method. The estimated parameters are presented in Table 4.2. When $T^* = T'$, $\lambda \to \infty$, and thus the probability density becomes a Dirac-delta function centered at 0°. Figure 4.4 shows the comparison of the fitted distribution with empirical histograms for two periods.



Figure 4.3 Displacement response trace to the El Centro Differential Array recording from the 1979 Imperial Valley earthquake. The period of the SDOF oscillator is (a) T' = 1.5 sec and (b) T' = 3 sec. The orientations of $Sa_{RotD100}$ along with the difference between these orientations at the two periods $(|\alpha^* - \alpha'|)$ is also shown.



Figure 4.4 Distribution of $|\alpha^* - \alpha'|$ as predicted by the truncated exponential model is compared with the normalized histogram for a) T = 2 sec and T' = 0.1 sec and b) T = 2 sec and T' = 1 sec.

Ť 0.01 0.02 0.03 0.05 0.07 0.10 0.15 0.20 0.25 0.30 0.40 0.01 ∞ 0.02 0.579 ∞ 0.03 0.186 0.188 ∞ 0.05 0.070 0.071 0.072 ∞ 0.07 0.042 0.042 0.042 0.041 ∞ ∞ 0.10 0.031 0.031 0.030 0.028 0.031 0.15 0.022 0.022 0.022 0.020 0.019 0.020 ∞ ∞ 0.20 0.021 0.021 0.021 0.019 0.017 0.015 0.019 0.25 0.020 0.019 0.019 0.17 0.016 0.014 0.013 0.021 ∞ 0.30 0.020 0.020 0.019 0.017 0.016 0.014 0.013 0.016 0.026 ∞ T' 0.40 0.020 0.020 0.020 0.016 0.015 0.011 0.010 0.013 0.015 0.019 ∞ 0.50 0.018 0.018 0.018 0.015 0.013 0.011 0.009 0.011 0.010 0.013 0.024 0.75 0.014 0.014 0.013 0.012 0.010 0.009 0.006 0.007 0.007 0.007 0.011 1.00 0.013 0.013 0.012 0.010 0.009 0.007 0.005 0.005 0.005 0.007 0.010 1.50 0.010 0.010 0.009 0.007 0.007 0.005 0.003 0.003 0.004 0.005 0.008 2.00 0.007 0.007 0.007 0.006 0.005 0.003 0.002 0.003 0.004 0.003 0.005 3.00 0.004 0.004 0.004 0.004 0.003 0.003 0.000 0.001 0.003 0.004 0.004 4.00 0.005 0.005 0.006 0.005 0.004 0.003 0.001 0.002 0.003 0.004 0.006 5.00 0.007 0.007 0.007 0.005 0.004 0.003 0.002 0.003 0.003 0.005 0.007 7.50 0.007 0.007 0.007 0.006 0.004 0.003 0.002 0.002 0.003 0.004 0.005 10.00 0.007 0.007 0.007 0.005 0.005 0.003 0.002 0.002 0.003 0.005 0.005

Table 4.2Estimated values of the parameter λ for the truncated exponential model.
The table is symmetric, or coefficient at row i and column j and coefficient
at row j and column i are same; therefore, only half of the coefficients are
shown.

							T [*]				
		0.50	0.70	1.00	1.50	2.00	3.00	4.00	5.00	7.50	10.0
	0.01										
	0.02										
	0.03										
	0.05										
	0.07										
	0.10										
	0.15										
	0.20										
	0.25										
	0.30										
T'	0.40										
	0.50	œ									
	0.75	0.016	œ								
	1.00	0.013	0.022	8							
	1.50	0.008	0.013	0.020	∞						
	2.00	0.007	0.011	0.015	0.024	∞					
	3.00	0.004	0.006	0.010	0.012	0.019	Ø				
	4.00	0.005	0.008	0.010	0.011	0.016	0.029	8			
	5.00	0.005	0.009	0.010	0.012	0.015	0.024	0.040	S		
	7 50	0.005	0.009	0.011	0.013	0.016	0.019	0.025	0 034	8	
	10.00	0.005	0.000	0.011	0.010	0.010	0.013	0.020	0.007	0.057	
	10.00	0.005	0.009	0.010	0.013	0.014	0.017	0.021	0.027	0.057	00
5 Sa at Arbitrary Orientations

A model to predict Sa in an arbitrary orientation is needed to compute single orientation conditional spectra. Here we study the Sa in an orientation ϕ° away from the $Sa_{RotD100}$ orientation. This Sa is referred hereafter as Sa_{ϕ} . An empirical model for the ratio of Sa_{ϕ}/Sa_{RotD50} is developed, which can be used as a multiplicative factor with a ground-motion model prediction of Sa_{RotD50} to get a prediction for Sa_{ϕ} . The spectral acceleration in each orientation was computed for all the ground-motion recordings used in this study. This dataset was used to empirically compute the geometric mean of the Sa_{ϕ}/Sa_{RotD50} . As the event terms from mixed effects regression for $ln(Sa_{RotD100}/Sa_{RotD50})$ were found to be close to 0, we ignored the interevent terms and pooled the data across different earthquakes, and estimated the Sa_{ϕ}/Sa_{RotD50} using geometric means of the pooled data. The $Sa_{RotD100}/Sa_{RotD50}$ values estimated using mixed effects regression (Table 3.1) and empirical geometric means (values corresponding to $\phi = 0$ in Table 5.1) vary slightly but are practically identical.

Figure 5.1 shows the modeled ratio for three different periods. As expected the ratio is highest at $\phi = 0$, where it is same as $Sa_{RotD100}$, and decreases with increase of ϕ . Table 5.1 presents the geometric mean of Sa_{ϕ}/Sa_{RotD50} at ϕ values from 0 to 90° at 5° intervals for 21 periods. Predictions at other periods and ϕ values can be found by interpolating these results.



Figure 5.1 The geometric mean of Sa_{ϕ}/Sa_{RotD50} as a function of ϕ for different periods.

							φ(degrees)				
		0	5	10	15	20	25	30	35	40	45
	0.01	1.192	1.188	1.175	1.154	1.127	1.096	1.061	1.026	0.993	0.963
	0.02	1.191	1.187	1.174	1.154	1.127	1.095	1.061	1.026	0.993	0.964
	0.03	1.188	1.184	1.171	1.151	1.124	1.093	1.059	1.025	0.992	0.963
	0.05	1.187	1.183	1.170	1.150	1.123	1.091	1.058	1.024	0.992	0.964
	0.07	1.187	1.183	1.170	1.150	1.123	1.091	1.058	1.024	0.992	0.965
	0.10	1.186	1.181	1.168	1.148	1.122	1.091	1.058	1.024	0.993	0.965
	0.15	1.196	1.192	1.179	1.159	1.133	1.101	1.067	1.032	0.998	0.967
	0.20	1.204	1.199	1.187	1.166	1.140	1.109	1.074	1.038	1.003	0.968
	0.25	1.213	1.209	1.196	1.176	1.149	1.117	1.082	1.044	1.006	0.969
	0.30	1.217	1.213	1.200	1.180	1.153	1.120	1.084	1.046	1.008	0.970
T'	0.40	1.227	1.222	1.209	1.189	1.162	1.129	1.093	1.053	1.013	0.972
	0.50	1.228	1.223	1.210	1.190	1.163	1.130	1.094	1.054	1.013	0.972
	0.75	1.236	1.232	1.219	1.198	1.171	1.138	1.100	1.059	1.017	0.974
	1.00	1.239	1.234	1.222	1.201	1.173	1.140	1.102	1.061	1.017	0.973
	1.50	1.236	1.231	1.219	1.198	1.171	1.138	1.100	1.059	1.016	0.973
	2.00	1.240	1.235	1.222	1.201	1.174	1.140	1.102	1.061	1.018	0.974
	3.00	1.247	1.243	1.229	1.209	1.180	1.146	1.108	1.066	1.021	0.975
	4.00	1.257	1.253	1.240	1.219	1.190	1.156	1.116	1.073	1.026	0.977
	5.00	1.264	1.259	1.246	1.225	1.196	1.161	1.121	1.077	1.029	0.979
	7.50	1.284	1.280	1.266	1.245	1.215	1.180	1.138	1.091	1.039	0.985
	10.00	1.290	1.286	1.272	1.250	1.221	1.184	1.141	1.093	1.041	0.985

Table 5.1Geometric mean of Sa_{ϕ}/Sa_{RotD50} at various values of ϕ and T.

						φ(degrees)				
		50	55	60	65	70	75	80	85	90
	0.01	0.939	0.919	0.903	0.891	0.882	0.874	0.869	0.865	0.864
	0.02	0.939	0.920	0.904	0.892	0.882	0.875	0.869	0.866	0.865
	0.03	0.940	0.921	0.906	0.893	0.884	0.877	0.872	0.868	0.867
	0.05	0.941	0.923	0.908	0.896	0.887	0.880	0.874	0.871	0.870
	0.07	0.942	0.923	0.908	0.896	0.887	0.879	0.874	0.871	0.870
	0.10	0.941	0.922	0.906	0.893	0.882	0.874	0.868	0.865	0.864
	0.15	0.939	0.915	0.895	0.880	0.867	0.858	0.851	0.847	0.845
	0.20	0.938	0.910	0.887	0.869	0.854	0.843	0.835	0.830	0.829
	0.25	0.935	0.905	0.879	0.858	0.841	0.828	0.819	0.813	0.812
	0.30	0.935	0.902	0.874	0.850	0.830	0.814	0.803	0.796	0.794
T'	0.40	0.934	0.899	0.868	0.841	0.819	0.802	0.789	0.781	0.779
	0.50	0.933	0.896	0.863	0.835	0.811	0.792	0.780	0.773	0.770
	0.75	0.933	0.893	0.857	0.825	0.798	0.776	0.761	0.752	0.749
	1.00	0.931	0.891	0.854	0.822	0.795	0.773	0.757	0.748	0.745
	1.50	0.932	0.892	0.855	0.823	0.795	0.773	0.757	0.748	0.744
	2.00	0.930	0.889	0.851	0.817	0.789	0.766	0.750	0.740	0.737
	3.00	0.929	0.885	0.845	0.809	0.778	0.753	0.734	0.723	0.719
	4.00	0.929	0.881	0.837	0.796	0.761	0.730	0.708	0.693	0.688
	5.00	0.928	0.877	0.828	0.781	0.740	0.704	0.677	0658	0.652
	7.50	0.928	0.869	0.810	0.753	0.699	0.650	0.608	0.577	0.565
	10.00	0.927	0.867	0.806	0.746	0.688	0.635	0.589	0.555	0.542

6 Example Target Spectra

As discussed above, the $Sa_{RotD100}$ spectrum is an envelope over spectra from all orientations at each period. Figure 4.3 shows that the $Sa_{RotD100}$ value may be observed in very different orientations, even at two periods which are close to each other. So, it is very unlikely to observe $Sa_{RotD100}$ at multiple periods in a single orientation. Thus, using $Sa_{RotD100}$ as a target design spectrum may result in conservative estimates of engineering demand parameters (EDPs), which depends on multiple periods (e.g., peak floor acceleration, interstory drift ratio, etc.). Conditional mean spectra approach (e.g., Baker [2011]) can be used to compute more realistic single orientation target spectra for design.

The conditional mean spectrum is the expected value of the ground-motion intensity conditioned upon some information. Here we study the computation of two such target spectra conditioned on a specific orientation and on a $Sa_{RotD100}$ observation in a specific period.

6.1 SPECTRA CONDITIONED ON ORIENTATION

Structures generally have different load resistance in different orientations. If some orientation is more important than other orientations, then the expected value of Sa in that particular orientation can be used as an appropriate target spectrum. Since this response spectrum is conditioned on a single orientation it does not suffer from the problem of having Sa from different orientations at different periods, as in case of the $Sa_{RotD100}$ spectra.

The target spectrum conditioned on an orientation, θ° away from strike-parallel orientation can be computed using the equation below

$$E[Sa | \theta] = \int_{0}^{90} E[Sa_{\theta} | \alpha] \cdot P(\alpha) d\alpha$$

=
$$\int_{0}^{90} E[Sa_{\theta-\alpha}] \cdot P(\alpha) d\alpha$$

=
$$\int_{0}^{90} \frac{Sa_{\theta-\alpha}}{Sa_{RotD50}} \cdot \hat{S}a_{RotD50} \cdot P(\alpha) d\alpha$$
 (6.1)

where α represents the orientation in which the $Sa_{RotD100}$ is observed at the period for which computation is being done and \widehat{Sa}_{RotD50} represents the Sa_{RotD50} prediction from a ground-motion model.

Table 5.1 gives the values of $Sa_{\theta-\alpha}/Sa_{RotD50}$ at different periods and $\phi = \theta - \alpha$ orientations. While Table 4.1 describes the probability distribution of α [i.e. $P(\alpha)$].

Spectra conditioned in the strike-normal and strike-parallel orientations are compared with corresponding Sa_{RotD50} and $Sa_{RotD100}$ in Figure 6.1. These computations were done for an earthquake of magnitude 7, at a site with a V_{S30} of 760m/sec, and located 2.5 km away from the rupture. The Boore and Atkinson [2008] model prediction was used to estimate Sa_{RotD50} [i.e., Sa_{RotD50} in Equation (6.1)]. It should be noted that Boore and Atkinson [2008] model gives prediction for $Sa_{GMRotI50}$ intensity, and conversion factors from Boore [2010] were used to convert the $Sa_{GMRotI50}$ intensities to Sa_{RotD50} .



Figure 6.1 Comparison of the median predicted $Sa_{RotD100}$ and Sa_{RotD50} spectra with spectra conditioned in strike-normal and strike-parallel orientations. All results are for an earthquake with magnitude 7, at distance of 2.5 km, and with a V_{s30} = 760 m/sec.

6.2 SPECTRA CONDITIONED ON THE ORIENTATION OF $Sa_{RotD100}$ AT A GIVEN PERIOD

Since, the orientation of $Sa_{RotD100}$ is random, the spectrum conditioned on a single orientation can never be as large as $Sa_{RotD100}$ at any period. Structural response is often primarily driven by the ground-motion intensity at a single period. Thus, if a single period is more important than others, a more appropriate target spectrum could be the one conditioned on the orientation in which $Sa_{RotD100}$ is observed at the important period (say T^*). If the spectrum is conditioned on $Sa_{RotD100}$ orientation at the period T^* (i.e., orientation = α^*), the expected value of the Sa at a different period, say T', can be computed using Equation (6.2):

$$E[SaT' | \alpha^*] = \int_0^{90} E[SaT' | \alpha', \alpha^*] P(\alpha' | \alpha^*) d\alpha'$$

$$= \int_0^{90} E[SaT'_{|\alpha^* - \alpha'|} | \alpha', \alpha^*] P(|\alpha' - \alpha^*|) d\alpha'$$

$$= \int_0^{90} \frac{Sa_{\alpha^* - \alpha'}}{Sa_{RotD50}} \hat{S}a_{RotD50} P(|\alpha' - \alpha^*|) d\alpha'$$
(6.2)

where $\frac{Sa_{\alpha^*-\alpha'}}{Sa_{RotD50}}$ is given by Table 5.1 for different values of $\phi = |\alpha^* - \alpha'|$ and periods (*T'*). \widehat{Sa}_{RotD50} is the prediction from a ground-motion model and $P(|\alpha' - \alpha^*|)$ is modeled by the truncated exponential distribution with the parameter λ for the pair of periods *T'* and *T*^{*} given in Table 4.2.

Spectra conditioned on the $Sa_{RotD100}$ orientations at $T^* = 0.2$ sec and $T^* = 1$ sec are compared with the Sa_{RotD50} and $Sa_{RotD100}$ in Figure 6.2. These computations were done for an earthquake of magnitude 7, at a site with a V_{S30} of 760m/sec, and located 2.5 km away from the rupture. Again the Boore and Atkinson [2008] model prediction was used to estimate Sa_{RotD50} .



Figure 6.2 Comparison of the $Sa_{RotD100}$ and Sa_{RotD50} spectra with spectra conditioned on $Sa_{RotD100}$ orientation at T = 0.2 sec and T = 1 sec. All results are for an earthquake with magnitude 7, at distance of 2.5 km, and a $V_{S30} = 760$ m/sec.

7 Conclusions

In this study, we examined different methods of representing the intensity of ground motion in the horizontal plane using a response spectrum that is a one-dimensional representation of ground-motion intensity. We focused on two orientation-independent representations of the response spectrum: Sa_{RotD50} and $Sa_{RotD100}$. The new ground-motion models being developed as part of the NGA-West2 project will predict the Sa_{RotD50} spectrum at a site due to a future earthquake, while the NEHRP [2009] provisions recommend using $Sa_{RotD100}$ for seismic design. We have proposed a model to predict the ratio of $Sa_{RotD100}$ to Sa_{RotD50} , which can be used as a multiplicative factor with the Sa_{RotD50} predictions from the new NGA-West2 ground-motion models to predict the $Sa_{RotD100}$ ground-motion intensity. The proposed model was compared and was found to be consistent with similar models built in the past, though the proposed model advances that earlier work by using a larger data set, utilizing the recently adopted Sa_{RotD50} definition instead of $Sa_{GMRotI50}$ and using mixed effects regression to account for inter-event terms. The differences between the proposed model and corresponding NEHRP [2009] ratios were also explained. One important observation from this work is that the current NEHRP ratio of 1.1 at small periods is incorrect and should be approximately 1.2; this result is confirmed by other studies, as was illustrated in Figure 3.2.

Along with modeling the ratio of $Sa_{RotD100}$ to Sa_{RotD50} , we also modeled the probability distribution of orientations in which the $Sa_{RotD100}$ intensity is observed relative to the strike of the fault. The orientations of $Sa_{RotD100}$ were observed to be uniformly distributed when the closest distance between the fault and the site was greater than 5 km, or if the period under consideration was less than 1 sec. Only for the cases when the site was within 5 km of the fault and at periods greater than 1 sec, the orientation of $Sa_{RotD100}$ was more likely to be closer to the strike-normal than strike-parallel direction. The relationship between the orientations of $Sa_{RotD100}$ at different periods was also studied, and the difference between the orientation was modeled using a truncated exponential distribution. Together these models can help solve a practical problem of converting between two important IMs while helping deepen the understanding of the directionality of ground motions by studying the distribution of orientations in which $Sa_{RotD100}$ occurs and dependence of the $Sa_{RotD100}$ to Sa_{RotD50} ratio on different seismological parameters. Spectra conditioned on an orientation and on the orientation in which $Sa_{RotD100}$ is observed at a particular period were discussed. Example computations of these spectra using the models developed in the study were also presented.

It is anticipated that these results will help bridge the gap between the work of seismic hazard analysts, who typically use Sa_{GM} or Sa_{RotD50} values, and design engineers, some of whom prefer to work with $Sa_{RotD100}$ response spectra.

8 Recommendations for Future Research

This report summarizes a comprehensive study of ground-motion directionality in accordance with the original goals of the NGA-West2 project. The study nonetheless raised some questions which were not resolved, and would benefit from future research as summarized below.

8.1 PHYSICS OF DIRECTIONALITY AND CONNECTIONS TO DIRECTIVITY

Though this report focuses on the statistical study of ground-motion directionality, the results raise important questions about the physical process behind ground-motion directionality. Most importantly, the results show that the connection between directivity and directionality may be weaker than intuitively expected. Directivity (in the context of S-waves) can cause preferential polarization of ground motion in the fault normal orientation, but directivity effects are not equally strong at all periods, fault distances, and orientations with respect to the fault. While the directionality effects studied here are remarkably uniform over variations in those conditions, as can be seen in Figures A.1 to A.8, directivity causes polarization in approximately fault-normal orientations; however, this study showed that there is no preferential orientation of $Sa_{RotD100}$ beyond 5 km of the fault. Even within km of the fault, the fault-normal polarization is weaker than that expected from directivity. Additionally, the $Sa_{RotD100}/Sa_{RotD50}$ ratios and the $Sa_{RotD100}$ orientations do not show any significant trend with directivity parameters (e.g., IDP and ξ), as shown in Appendix A. In summary, occurrence of high $Sa_{RotD100}/Sa_{RotD50}$ ratios does not appear to be related to occurrence of directivity; therefore, the directionality models proposed here do not account for the impact of directivity on ground motions. Many of these observations were first noted by Watson-Lamprey and Boore [2007], and they suggest that further research is needed to describe the physical processes, if any, behind ground-motion directionality.

8.2 INPUT GROUND MOTIONS FOR NONLINEAR DYNAMIC ANALYSIS

Target response spectra are used widely in earthquake engineering, both as targets for groundmotion selection and scaling, or for other related assessment procedures. Engineering codes and technical groups have recently debated at length the relative merits of using Sa_{RotD50} or $Sa_{RotD100}$ to define a target spectrum. Two related conditional target spectra were suggested in this study, but their impact on results from engineering analyses was not considered. Further study is required to evaluate the impact of using different target spectra considered herein. Some results from the study raise interesting questions about the orientation in which selected ground-motions should be input to a dynamic analysis model. Damage is driven by a variety of response parameters, (e.g., story drift ratios, floor accelerations) and different parameters are generally sensitive to spectral acceleration at different periods. Results from this study show that the orientation of maximum *Sa* frequently differs with period. It is not clear which orientation of the input ground-motion causes maximum damage when damage is sensitive to a range of periods, and there is ongoing debate regarding how to use $Sa_{RoiD100}$ to select and scale motions in a manner that reflects properties of real ground motions. Further research on these topics would be useful for developing recommendations that utilize our current knowledge of directionality.

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Appendix A: Dependence of $Sa_{RotD100}/Sa_{RotD50}$ on Seismological Parameters

This appendix contains figures showing the dependence of $Sa_{RotD100}/Sa_{RotD50}$ ratio on several seismological parameters. Each figure shows the scatter plot of $Sa_{RotD100}/Sa_{RotD50}$ ratios computed using a subset of NGA-West2 database being used to develop the Abrahamson-Silva ground-motion model. Median $Sa_{RotD100}/Sa_{RotD50}$ ratios from Table 3.1, and a non-parametric moving average model computed using LOESS smoothing (e.g., Hastie et al. [2001]) are also shown.



Figure A.1 Dependence of $Sa_{RotD100}/Sa_{RotD50}$ on closest distance between site and the rupture surface (*R*). Figures are shown for spectral acceleration periods of (a) 0.01 sec, (b) 0.1 sec, (c) 1 sec, and (d) 5 sec. The median $Sa_{RotD100}/Sa_{RotD50}$ ratios are taken from Table 3.1, and the nonparametric estimate is computed using LOESS smoothing (e.g., Hastie et al., 2001).



Figure A.2 Dependence of $Sa_{RotD100}/Sa_{RotD50}$ on earthquake magnitude (*M*). Figures are shown for spectral acceleration periods of (a) 0.01 sec, (b) 0.1 sec, (c) 1 sec, and (d) 5 sec. The median $Sa_{RotD100}/Sa_{RotD50}$ ratios are taken from Table 3.1, and the nonparametric estimate is computed using LOESS smoothing (e.g., Hastie et al. [2001]).



Figure A.3 Dependence of $Sa_{RotD100}/Sa_{RotD50}$ on s, the length of rupture between the epicenter and the point on fault closest to the site [Somerville et al 1997], for strike-slip faults. Figures are shown for spectral acceleration periods of (a) 0.01 sec, (b) 0.1 sec, (c) 1 sec, and (d) 5 sec. The median $Sa_{RotD100}/Sa_{RotD50}$ ratios are taken from Table 3.1 and the nonparametric estimate is computed using LOESS smoothing (e.g., Hastie et al. [2001]).



Figure A.4 Dependence of $Sa_{RotD100}/Sa_{RotD50}$ on *d*, the length of rupture between the hypocenter and the point on fault closest to the site [Somerville et al. 1997], for non-strike-slip faults. Figures are shown for spectral acceleration periods of (a) 0.01 sec, (b) 0.1 sec, (c) 1 sec, and (d) 5 sec. The median $Sa_{RotD100}/Sa_{RotD50}$ ratios are taken from Table 3.1, and the nonparametric estimate is computed using LOESS smoothing (e.g., Hastie et al. [2001]).



Figure A.5 Dependence of $Sa_{RotD100}/Sa_{RotD50}$ on θ , the angle between the line joining the epicenter with the site and the strike of the fault [Somerville et al., 1997], for strike-slip fault. Figures are shown for spectral acceleration periods of (a) 0.01 sec, (b) 0.1 sec, (c) 1 sec, and (d) 5 sec. The median $Sa_{RotD100}/Sa_{RotD50}$ ratios are taken from Table 3.1, and the nonparametric estimate is computed using LOESS smoothing (e.g., Hastie et al. [2001]).



Figure A.6 Dependence of $Sa_{RotD100}/Sa_{RotD50}$ on $\cos(\theta)$ for strike-slip faults. Figures are shown for spectral acceleration periods of (a) 0.01 sec, (b) 0.1 sec, (c) 1 sec, and (d) 5 sec. The median $Sa_{RotD100}/Sa_{RotD50}$ ratios are taken from Table 3.1, and the nonparametric estimate is computed using LOESS smoothing (e.g., Hastie et al., 2001).



Figure A.7 Dependence of $Sa_{RotD100}/Sa_{RotD50}$ on Spudich and Chiou's directivity parameter, IDP [Spudich et al. 2012]. Figures are shown for spectral acceleration periods of (a) 0.01 sec, (b) 0.1 sec, (c) 1 sec, and (d) 5 sec. The median $Sa_{RotD100}/Sa_{RotD50}$ ratios are taken from Table 3.1, and the nonparametric estimate is computed using LOESS smoothing (e.g., Hastie et al. [2001]).



Figure A.8 Dependence of $Sa_{RotD100}/Sa_{RotD50}$ on Rowshandel's directivity parameter, ξ [Spudich et al. 2012]. Figures are shown for spectral acceleration periods of (a) 0.01 sec, (b) 0.1 sec, (c) 1 sec, and (d) 5 sec. The median $Sa_{RotD100}/Sa_{RotD50}$ ratios are taken from Table 3.1, and the nonparametric estimate is computed using LOESS smoothing (e.g., Hastie et al. [2001]).

Appendix B: Dependence of Sa_{RotD100} Orientation on Directivity Parameters

This appendix contains figures showing histograms of the orientations with respect to the strike of the fault (α) in which $Sa_{RotD100}$ was observed. The histograms are binned into different distance and directivity parameter bins.



Figure B.1 Probability density of α ($Sa_{RotD100}$ orientations) in different *R*, and Spudich and Chiou's directivity parameter (IDP) bins. The distance between site and fault rupture (*R*) is the primary factor affecting α , among the two factors considered here.



Figure B.2 Probability density of α ($Sa_{RotD100}$ orientations) in different R, and Rowshandel's directivity parameter (ξ) bins. The distance between site and fault rupture (R) is the primary factor affecting α , among the two factors considered here.

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